

Operation of HV-MAPS detectors in vacuum

Heinrich Leithoff

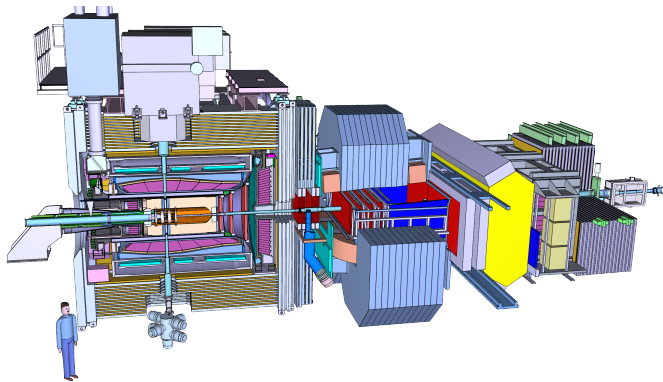
Mainz

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Helmholtz Institute Mainz

\bar{P} ANDA at FAIR

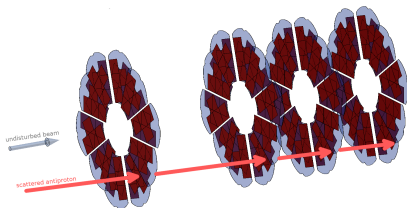
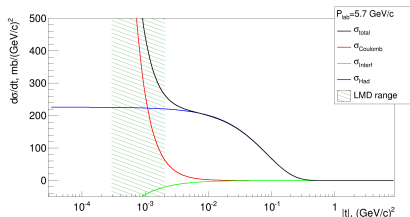


1.5 GeV/c to 15 GeV/c beam momentum, main research areas:

- Hadron spectroscopy
- Hadrons in matter
- Hypernuclei
- Nucleon structure

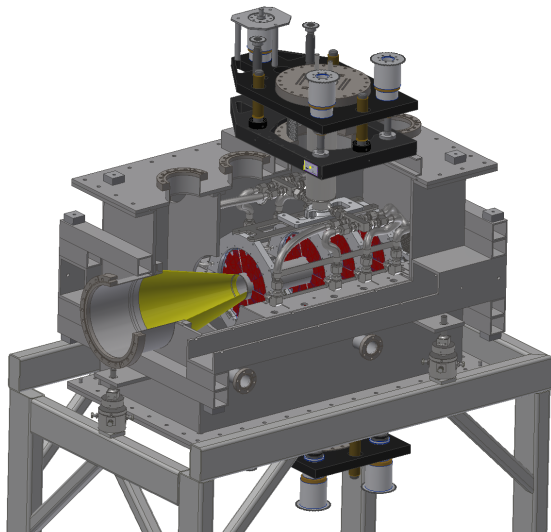
Precise luminosity needed \Rightarrow dedicated detector 11 m after IP

Luminosity measurement at \bar{P} ANDA



- Luminosity determination from elastic scattering
- Coulomb part dominant at low momentum transfer
- Measurement at very small scattering angles (3 mrad to 8 mrad) after two magnetic fields \Rightarrow tracking detector
- Required precision: 1% for relative and 5% for absolute luminosity
- Very sensitive to multiple scattering
- Low material budget \Rightarrow sensors in vacuum

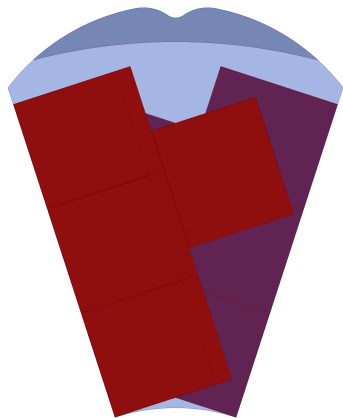
Luminosity detector technical overview



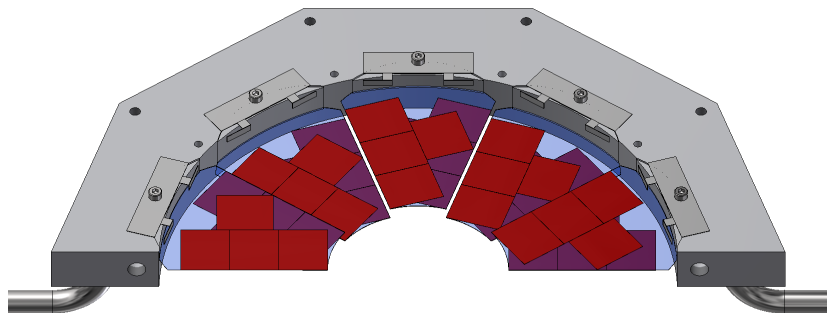
- Sensors in secondary vacuum
- Low material budget and active cooling
- Retractable during beam tuning
- Precise position necessary
- Modular design
- Vacuum box ~ 1 m long

Module

- Active sensors thinned to $50\ \mu\text{m}$ with $20\ \text{mm} \times 20\ \text{mm}$ active area: up to $400\ \text{mW cm}^{-2}$ expected
 - Low material budget: active cooling outside of detector acceptance
- ⇒ 8 Sensors glued on a $200\ \mu\text{m}$ thick CVD-diamond wafer to form a “module”
- Diamond: very high thermal conductivity, low material budget
 - Low viscosity glue allows thickness of $\sim 10\ \mu\text{m}$
 - Aluminium trace flexcables with $< 30\ \mu\text{m}$ aluminium
 - Cooling by thermal conductivity ⇒ large thermal gradient on the module

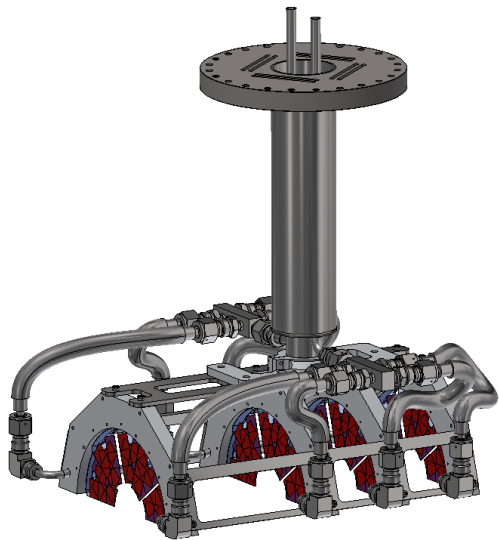


Half Plane



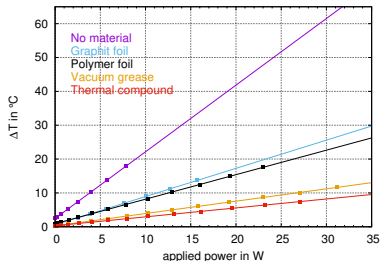
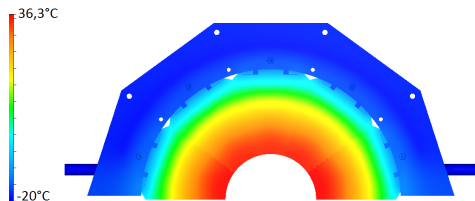
- Modules clamped in aluminium heatsink
 - Aluminium heatsink actively cooled by integrated cooling pipe
 - First electronics needed closeby (~ 10 cm)
- ⇒ PCB clamped to aluminium heatsink
- Module placement staggered to avoid module collision

Half detector



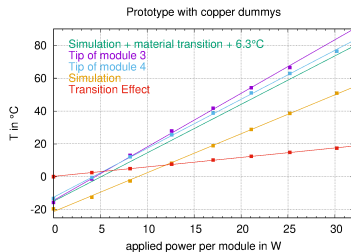
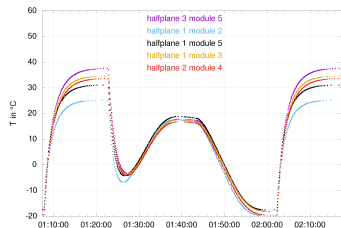
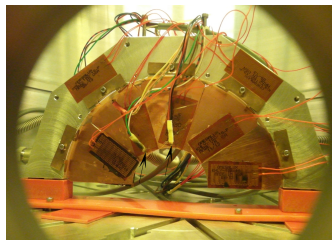
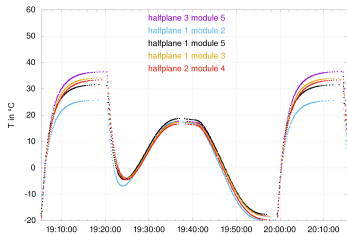
- Four half planes connected to a half detector
- Common feedthrough for cooling lines
- Shape measured by stationary CMM → good knowledge of sensor position in half detector

Half Plane cooling



- Worst case assumption: 700 mW cm^{-2} heatload from sensors, resistive losses in cables, about 50 W per half plane from electronics
- ⇒ Large gradient on module: $>50 \text{ }^\circ\text{C}$, difference between modules $<2 \text{ }^\circ\text{C}$
- Not included in simulation: transition effect between parts
 - Contact materials measured, vacuum grease is preferred

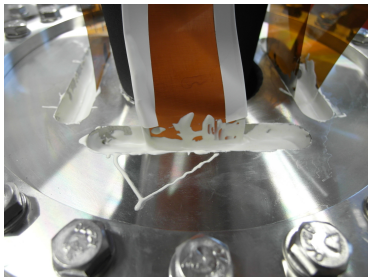
Cooling tests



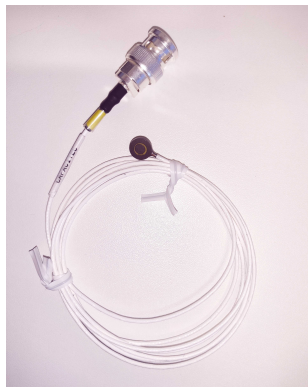
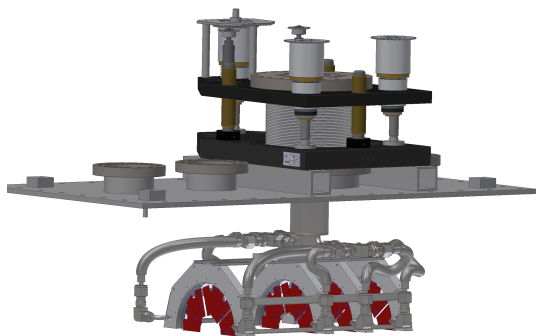
- Half plane consistent with simulation
- Long term test of half detector cooling: no aging after >1000 cycles

Concept of peripherie (feedthrough)

- ~ 2000 traces per half detector, including up to 640 LVDS pairs
- ⇒ Glued in flexcables as high density option, first test promising
- Additional benefit in main feedthrough flange: no movement relative to the half detector
 - LV feedthrough per half detector extra, high power (~ 200 A) needed

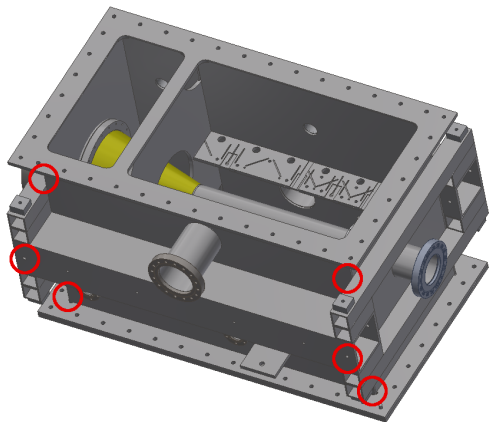


Movable detector: position problems and solutions



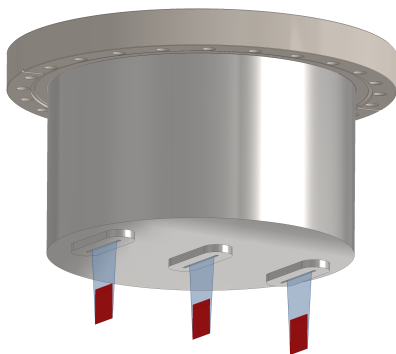
- Half detector mounted on LSM for movement
 - Problem 1: position of half detector after movement?
- ⇒ Capacitive sensors in vacuum box measuring against half detector, resolution $< 2 \mu\text{m}$

Movable detector: position problems and solutions 2



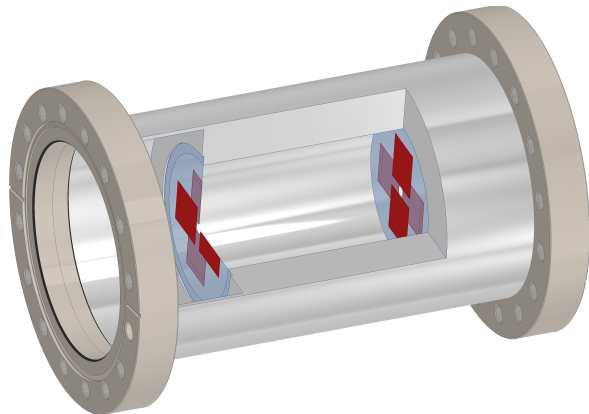
- Problem 2: Position of the capacitive sensors in the vacuum box?
⇒ Measurement of the sensor position relative to markers on the outside with a portable CMM (measurement arm), resolution $< 28 \mu\text{m}$
- Mechanical stability of vacuum box relevant!

Technology transfer to PRES: MicroLumi



- Based on CF200 flange, moveable by LSM
- Three modules with one sensor each, glued on diamond wafer
- Cable and diamond glued into custom flange \Rightarrow cooling and first electronics outside the vacuum (~ 10 cm distance to sensors)

Technology Transfer to PRES: Option B



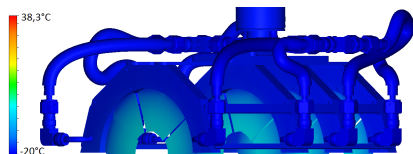
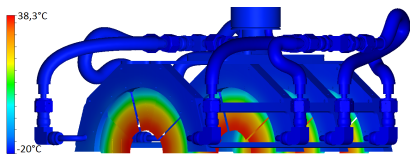
- Integrated in beampipe, no moveable parts
- Precise detector positioning and beam control needed
- Diamond wafer clamped into vacuum chamber, cooling from outside

Backup

Heat loads and simulation

Expected heat dissipation per half detector:

	sensors	resistance in flexcables	LDO Voltage regulator	Multiplexer etc.
worst case	520 W	80 W	160 W	~50 W
likely case	190 W	10 W	60 W	~50 W



- simulated maximum temperature: 39 °C / 0 °C
- neglected in the simulations: material transitions, radiative effects
- additional temperature rise of 11 °C / 4 °C estimated from measurements