# Discrete scale-invariant boson-fermion duality in one dimension

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25th European Conference on Few-Body Problems in Physics July 30–August 4, 2023, Mainz Introduction

- Today I am going to talk about discrete scale invariance in N-body problems of identical particles in one dimension.
- Before doing this, I will first discuss the impact of scale invariance in quantum many-body problems.

#### Discrete scale-invariant S-matrix theory: A toy example

- Consider a  $1 \times 1$  S-matrix  $S(E) \in U(1)$ , where E stands for energy.
- The most general scaling law consistent with unitarity |S(E)| = 1 is

$$S(E) = S(e^{t} E) \quad (t : real parameter)$$
(1)

- Depending on the range of t, there exist two types of solutions to eq. (1):
- Case t ∈ ℝ = (-∞,∞): Continuous scale invariance. In this case, there is only a constant solution:

$$S(E) = \text{const} \tag{2}$$

Hence, in continuous scale-invariant theory, S-matrix must be trivial.

- Case t ∈ t<sub>\*</sub>ℤ = {0, ±t<sub>\*</sub>, ±2t<sub>\*</sub> · · · }: Discrete scale invariance. In this case, S-matrix can be nontrivial. In fact, as we will see next, we can prove the following:
  - log-periodicity of S(E)
  - emergence of geometric sequence of bound states

• Log-periodicity of S-matrix. First, observe that the scale transformation for E is equivalent to the constant shift for  $\log E$ :

$$E \mapsto e^{nt_*} E \quad \Leftrightarrow \quad \log E \mapsto \log E + nt_*$$
 (3)

The general solution to the scaling law  $S(E) = S(e^{nt_*} E)$  is therefore

$$S(E) = f(\log E) \tag{4}$$

where  $f(x) = f(x + t_*)$  is a periodic function with the period  $t_*$ . Hence, in discrete scale-invariant theory, S-matrix must be a periodic function of  $\log E$ .

 Geometric sequence of bound states. Suppose that S(E) has a simple pole (bound-state pole) at E = -E<sub>\*</sub>:

$$S(E) = \frac{N_*}{E + E_*} + O(1) \text{ as } E \to -E_*$$
 (5)

Then, the scaling law implies there exist infinitely many poles of the form:

$$S(E) = S(e^{nt_*} E) = \frac{N_* e^{-nt_*}}{E + E_* e^{-nt_*}} + O(1)$$
(6)

This implies the existence of infinitely many bound states with the binding energies  $E_n = -E_* e^{-nt_*}$ , which satisfy  $E_{n+1} = E_n e^{-t_*}$ . Hence, in discrete scale-invariant theory, bound states must form a geometric sequence.

- As we have seen, typical predictions of discrete scale-invariant theory are:
  - periodic oscillation of S-matrix as a function of  $\log E$
  - geometric sequence of bound states
- And a typical example realizing these features is the Efimov effect for three identical bosons with two-body short-range interactions [Efimov '70], where the three-body bound-state energies satisfy

$$E_{n+1} = E_n e^{-t_*}, \quad e^{-t_*} \approx (22.7)^{-2}$$
 (7)

This result is independent of the details of interactions and hence universal.

- Note, however, that the appearance of the Efimov effect highly depends on spatial geometry and particle statistics.
- For example, for systems of identical bosons with two-body contact interactions, it was shown that the Efimov effect appears only if the spatial dimension d is in the range 2.3 < d < 3.8 [Nielsen-Fedorov-Jensen-Garrido '01].
- For systems of identical fermions with two-body contact interactions, the Efimov effect was not realized in lower dimensions.

- In this work, I revisited N-body problems of identical particles in one dimension, where interparticle interactions are only two-body contacts.
- First, I classified all possible two-body contact interactions that respect:
  - unitarity (probability conservation)
  - permutation invariance (indistinguishability of identical particles)
  - translation invariance (total momentum conservation)
  - scale invariance

[Note: I did not impose the cluster-decomposition property, which was (implicitly) assumed in the previous works.]

- Then, I showed that, for both bosonic and fermionic systems, continuous scale invariance can be broken to discrete scale invariance for any  $N \ge 3$ .
- Further, I derived the exact N-body bound-state spectrum as well as the exact N-body S-matrix elements for any N ≥ 3.
- In the rest of the talk, I will explain these results briefly.
- The key is the boson-fermion duality.

Boson-fermion duality in one dimension

- In one dimension, any bosonic N-body problem has its fermionic dual.
- Typical examples are the following:
  - Lieb-Liniger model (bosonic model) [Lieb-Liniger '63]

$$H = -\frac{\hbar^2}{2m} \sum_{j=1}^{N} \frac{\partial^2}{\partial x_j^2} + \frac{\hbar^2}{m} \sum_{1 \le j < k \le N} \delta(x_j - x_k; g_{\mathsf{B}})$$
(8)

• Cheon-Shigehara model (fermionic model) [Cheon-Shigehara '98]

$$H = -\frac{\hbar^2}{2m} \sum_{j=1}^N \frac{\partial^2}{\partial x_j^2} + \frac{\hbar^2}{m} \sum_{1 \le j < k \le N} \varepsilon(x_j - x_k; g_{\mathsf{F}})$$
(9)

Here  $\delta(x;g_{\rm B})$  and  $\varepsilon(x;g_{\rm F})$  are defined by

$$\delta(x;g_{\rm B}) = g_{\rm B}\delta(x) \tag{10a}$$

$$\varepsilon(x;g_{\mathsf{F}}) = \lim_{a \to 0} \left(\frac{1}{2g_{\mathsf{F}}} - \frac{1}{2a}\right) \left(\delta(x+a) + \delta(x-a)\right) \tag{10b}$$

• When  $g_{\rm B} = 1/g_{\rm F}$ , these models become equivalent and satisfy (i) spectral equivalence, (ii) boson-fermion mapping, and (iii) strong-weak duality.

 In one dimension, we can classify all possible two-body contact interactions that respect unitarity, permutation invariance, and translation invariance. The result is [Ohya '21]

$$H_{\mathsf{B}/\mathsf{F}} = -\frac{\hbar^2}{2m} \sum_{j=1}^N \frac{\partial^2}{\partial x_j^2} + V_{\mathsf{B}/\mathsf{F}}(x_1, \cdots, x_N)$$
(11)

where

$$V_{\mathsf{B}} = \frac{\hbar^2}{m} \sum_{j=1}^{N-1} \sum_{\sigma \in A_N} \left[ \prod_{k \in \{1, \cdots, N-1\} \setminus \{j\}} \theta(x_{\sigma(k)} - x_{\sigma(k+1)}) \right] \delta(x_{\sigma(j)} - x_{\sigma(j+1)}; g_{\mathsf{B}j})$$

$$(12a)$$

$$V_{\mathsf{F}} = \frac{\hbar^2}{m} \sum_{j=1}^{N-1} \sum_{\sigma \in A_N} \left[ \prod_{k \in \{1, \cdots, N-1\} \setminus \{j\}} \theta(x_{\sigma(k)} - x_{\sigma(k+1)}) \right] \varepsilon(x_{\sigma(j)} - x_{\sigma(j+1)}; g_{\mathsf{F}j})$$

$$(12b)$$

Here  $A_N$  stands for the alternating group of order N!/2.

• When  $g_{Bj} = 1/g_{Fj}$ , these models become dual to each other. Further, if  $g_{B/Fj}$  has a certain coordinate dependence, these models become scale invariant. In addition, for sufficiently strong attractive interactions, continuous scale invariance can be broken to discrete scale invariance.

• In the discrete scale-invariant phase, the *N*-body Schrödinger equation can be reduced to the following one-body problem on the half line with the attractive inverse square potential:

$$\left(-\frac{d^2}{dr^2} + \frac{-\nu^2 - \frac{1}{4}}{r^2}\right)\psi(r) = \frac{2mE}{\hbar^2}\psi(r)$$
(13)

where E stands for the energy of N-body relative motion,  $\nu>0$  is a constant determined by coupling strengths, and r is the hyperradius defined by

$$r = \sqrt{\frac{1}{N} \sum_{1 \le j < k \le N} (x_j - x_k)^2}$$
(14)

By solving eq. (13), we can obtain the exact solutions of  $N\-$  body problem. The results are as follows:

• Exact N-body bound-state spectrum

$$E_n = -E_* \exp\left(-\frac{2n\pi}{\nu}\right) \tag{15}$$

• Exact *N*-body S-matrix elements

$$S(E) = \frac{1}{i} \frac{\sin\left(\frac{\nu}{2}\log\left(\frac{E}{E_*}\right) + \frac{i\nu\pi}{2}\right)}{\sin\left(\frac{\nu}{2}\log\left(\frac{E}{E_*}\right) - \frac{i\nu\pi}{2}\right)}$$
(16)

## Summary and outlook

### Summary

- I classified all possible two-body contact interactions that respect:
  - unitarity
  - permutation invariance
  - translation invariance
  - scale invariance
- By using those two-body contact interactions, I constructed  $N\mbox{-boson}$  and  $N\mbox{-fermion}$  models that exhibit:
  - boson-fermion duality
  - breakdown of continuous scale invariance to discrete scale invariance
- I derived the exact N-body bound-state spectrum as well as the exact N-body S-matrix elements in the discrete scale-invariant phase.

## Outlook

- Generalization to (non)identical particles with internal degrees of freedom.
- Construction of field-theory description.